

EE234

Microprocessor Systems

Final Exam

Dec. 12, 2019. (3:10pm – 5:10pm)

Instructor: Dae Hyun Kim (daehyun@eecs.wsu.edu)

Name:

WSU ID:

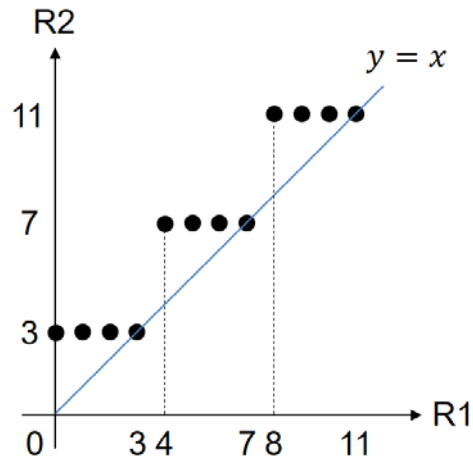
Problem	Points	
1	10	
2	10	
3	10	
4	10	
5	10	
6	10	
7	20	
8	20	
9	10	
Total	110	

Problem #1 (Bit manipulation, 10 points)

Suppose R# is an 8-bit register. The data stored in R# is treated as an unsigned binary number. Draw a graph for the following instruction. The x-axis should be the value stored in R1 and the y-axis should be the value stored in R2.

OR R2, R1, #0x03

The two LSBs are always 1. Thus, $x_7 \dots x_2x_1x_0$ is mapped to $x_7 \dots x_211$.



Problem #2 (Bit manipulation, 10 points)

Suppose R# is an 8-bit register. The data stored in R# is treated as an unsigned binary number. We want to calculate the following for given input R_1 (% is the MOD operation):

$$R_2 = 240 + 2 * (R_1 \% 16) - R_1$$

R_1 is stored in register R1 (input) and R_2 is the result that will be stored in register R2. The above function can be implemented by a single assembly instruction with a certain constant C as follows:

R2, R1, #C

Find the instruction and the constant. Notice that the instruction is one of the instructions shown in the last page. Hint: Express $R_2 = y_7 \dots y_0$ with respect to $R_1 = x_7 \dots x_0$. Then, find the relationship between R2 and R1.

Suppose $R_1 = x_7 x_6 \dots x_1 x_0$ and $R_2 = y_7 y_6 \dots y_1 y_0$.

$$R_1 \% 16 = 0000x_3x_2x_1x_0$$

$$R_1 + R_2 = 240 + 2 * (R_1 \% 16) = 0xF0 + x_3x_2x_1x_0 + x_3x_2x_1x_0$$

$$\begin{array}{r}
 x_7 \ x_6 \ x_5 \ x_4 \ x_3 \ x_2 \ x_1 \ x_0 \\
 + \ y_7 \ y_6 \ y_5 \ y_4 \ y_3 \ y_2 \ y_1 \ y_0 \\
 \hline
 1 \ 1 \ 1 \ 1 \ 0 \ 0 \ 0 \ 0 \\
 + \ 0 \ 0 \ 0 \ 0 \ x_3 \ x_2 \ x_1 \ x_0 \\
 + \ 0 \ 0 \ 0 \ 0 \ x_3 \ x_2 \ x_1 \ x_0
 \end{array}$$

Thus, R2 should be $\overline{x_7x_6x_5x_4}x_3x_2x_1x_0$. To obtain this from R1, we need $R_1 \oplus 0xF0$.

Answer: instruction = EOR, constant C = 0xF0

EOR R2, R1, #0xF0

Problem #3 (Assembly, 10 points)

All the registers R# are 32-bit registers. "int" is a 32-bit signed integer data type. Write an assembly code for the "for" loop in the following C code.

```
int x[30]; // given
int y[30];
```

```
// write an assembly code for the following for loop.
for ( int i = 0 ; i < 30 ; i++ )
    y[i] = x[i];
```

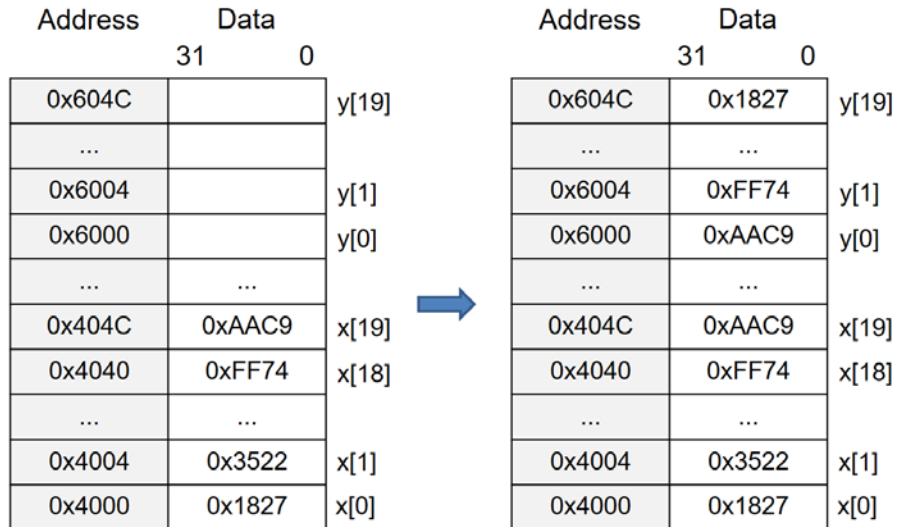
- &(x[0]): 0x4000
- &(y[0]): 0x5000

```
LDR R1, =0x4000
LDR R2, =0x5000
MOV R4, #0
```

```
loop:
LDR R3, [R1]
STR R3, [R2]
ADD R1, R1, #4
ADD R2, R2, #4
ADD R4, R4, #1
CMP R4, 30
BNE loop
```

Problem #4 (Assembly, 10 points)

All the registers R# are 32-bit registers. The following (left) shows an array x of 32-bit data and an array y of 32-bit data. Each of them has 20 elements. Now, we want to copy the data as shown in the figure.



Write an assembly code for the data copy. Basically it does the following:

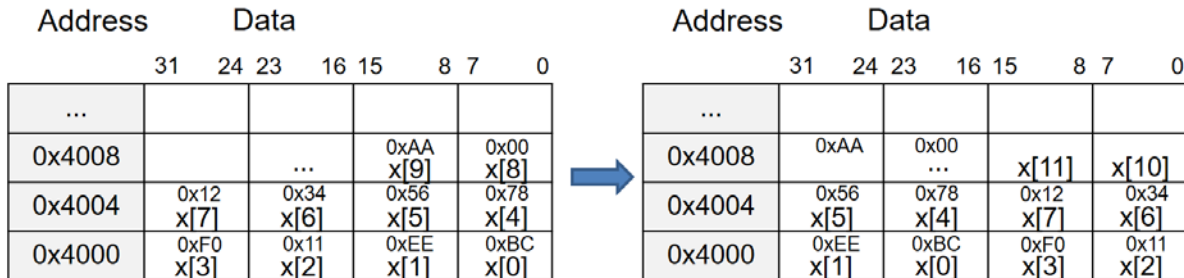
```
for ( int i = 0 ; i < 20 ; i++ )
    y[19-i] = x[i];
```

```
LDR R1, =#0x4000 // MOV R1, #0x4000 is acceptable.
LDR R2, =#0x604C
```

```
loop:
    LDR R3, [R1]
    STR R3, [R2]
    ADD R1, R1, #4
    SUB R2, R2, #4
    CMP R1, #4050
    BNE loop
```

Problem #5 (Assembly, 10 points)

The “unsigned char” data type is used for an 8-bit (one-byte) data. However, we cannot access them individually unless they are word-aligned. See the following example.



Suppose you declare “unsigned char x[20];” as shown above (left). Then, the address of x[0] is 0x4000, that of x[1] is 0x4001, that of x[2] is 0x4002, etc. However, the addresses like 0x4001 and 0x4002 are not word-aligned (i.e., not integer multiples of 4), so you cannot access them using something like “LDR R1, =#0x4001” and “LDR R2, [R1]”. All the addresses must be word-aligned (integer multiples of 4).

Write an assembly code to rearrange the given data “unsigned char x[20]” as shown above (right). Notice that it is just rearranging the data. It does not change the address of the array, i.e., &(x[0]) is still 0x4000, &(x[1]) is still 0x4001, etc. after the rearrangement.

```

LDR R1, =#0x4000
loop:
LDR R2, [R1]
MOV R3, R2
LSL R2, #16 // R2 = x[1] x[0] 0x0000
LSR R3, #16 // R3 = 0x0000 x[3] x[2]
OR R2, R2, R3 // R2 = x[1] x[0] x[3] x[2]
STR R2, [R1]
ADD R1, R1, #4
CMP R1, #0x4014
BNE loop
end:
// end

```

Problem #6 (C, 10 points)

All the registers R# are 32-bit registers and everything is based on the 32-bit ARM architecture. How many bytes will C actually use for the following code (including the memory space for x in the stack)?

```
int*** x = new int**[2];
```

```
x[0] = new int*[3];
```

```
x[1] = new int*[4];
```

```
x[0][0] = new int[2];
```

```
x[0][1] = new int[3];
```

```
x[0][2] = new int[2];
```

```
x[1][0] = new int[2];
```

```
x[1][3] = new int[5];
```

x: 4B.

x[0], x[1]: $4B \cdot 2 = 8B$

x[0][0], x[0][1], x[0][2]: $4B \cdot 3 = 12B$

x[1][0], x[1][1], x[1][2], x[1][3]: $4B \cdot 4 = 16B$

x[0][0], x[0][1], x[0][2]: $4B \cdot (2+3+2) = 28B$

x[1][0], x[1][3]: $4B \cdot (2+5) = 28B$

Total: 96 Bytes

Problem #7 (C, 20 points)

All the registers R# are 32-bit registers and everything is based on the 32-bit ARM architecture. The following map shows a part of the main memory. The data type of variable “x” is int**. “x” is declared by

```
int** x = new int*[a];

for ( int i = 0 ; i < a ; i++ )
    x[i] = new int[b];
```

for given constants “a” and “b”. Currently, the value of x is 0x4000 as shown in the figure.

Address	Data	
		31 0
0x8000	0x4000	x
...		
0x402C	0x4000	
0x4028	0x402C	
0x4024	0x4028	
0x4020	0x4024	
0x401C	0x4020	
0x4018	0x401C	
0x4014	0x4018	
0x4010	0x4014	
0x400C	0x4010	
0x4008	0x4024	
0x4004	0x4014	
0x4000	0x400C	

- (a) What is the value of *x? **0x400C**
- (b) What is the value of &x? **0x8000**
- (c) What is the value of x+2? **0x4008**
- (d) What is the value of *(x+1)? **0x4014**

(e) What is the value of **x?

0x4010

(f) What is the value of *((*x) + ((int*) 0x10))?

***(0x400C + 0x0010) = *(0x401C) = 0x4020**

(g) What is the value of **(x+2)?

***(0x4008) = *(0x4024) = 0x4028**

(h) What is the value of x[0][0]?

0x4010

(i) What is the value of x[0][1]?

0x4014

(j) What is the value of x[1][1]?

0x401C

Problem #8 (C, 20 points)

All the registers R# are 32-bit registers and everything is based on the 32-bit ARM architecture. "int" is a 32-bit data type.

Write an assembly code for the above C code.

- `&(src[0][0].x[0])`: 0x8000
- The value stored in "des": 0x4000

*// Size of MyData: 24 bytes (6 * 4 bytes)*

LDR R1, =#0x8000 // src

LDR R2, =#0x4000 // des

MOV R3, #0 // a

loop_a:

MOV R4, #0 // b

loop_b:

MUL R5, R3, #72 // src[a]

ADD R5, R5, R1

MUL R6, R4, #24

ADD R5, R5, R6 // src[a][b]

ADD R5, R5, #4 // src[a][b].x[1]

*MUL R7, R3, #4 // 4*a*

*ADD R6, R2, R7 // des + 4*a*

LDR R7, [R6] // des[a]

MUL R6, R4, #24

ADD R7, R7, R6 // des[a][b]

ADD R7, R7, #4 // des[a][b].x[1]

LDR R8, [R5]

STR R8, [R7]

ADD R4, R4, #1 // b++

CMP R4, #3

BNE loop_b

ADD R3, R3, #1 // a++

CMP R3, #3

BNE loop_a

```
struct MyData {
```

```
    int x[4];
```

```
    int y[2];
```

```
};
```

```
MyData src[3][3]; // given
```

```
MyData** des = new MyData*[3];
```

```
for ( int i = 0 ; i < 3 ; i++ )
```

```
    des[i] = new MyData[3];
```

```
for ( int a = 0 ; a < 3 ; a++ ) {
```

```
    for ( int b = 0 ; b < 3 ; b++ ) {
```

```
        des[a][b].x[1] = src[a][b].x[1];
```

```
    }
```

```
}
```

Problem #9 (Interrupts, 10 points)

An ARM C source handles keyboard inputs using interrupts and an interrupt handler function H . Whenever a key input is received, the system generates an interrupt and H is called to process the input. The runtime of executing H for a key input is 1,000 clock cycles. The system clock frequency is 100MHz (period: 10ns). If two key inputs k_2 and k_3 are received while H is being executed to process a key input k_1 , the CPU stores k_2 and k_3 in its input buffer (queue). When H finishes processing k_1 , H is immediately executed again to process k_2 , then executed again to process k_3 . The size of the keyboard buffer is 20, i.e., it can store maximum 20 key inputs while H is being executed. If the buffer is full, any additional key inputs are ignored (discarded).

Suppose you press 100 keys periodically (i.e., you press a key at time 0, a key at time T , a key at time $2T$, ..., a key at time $99T$). Calculate the minimum T that does not cause discarded keystrokes for the 100 keyboard inputs (this is finding the maximum keystroke speed).

When the 100th key is pressed, H must be processing the 80th key so that the buffer has 19 inputs and the 100th input is inserted into the buffer. Processing a key takes $1000 \cdot 10\text{ns} = 10\mu\text{s}$. Processing 79 keys takes $790\mu\text{s}$. This must be smaller than the time when the 100th key is pressed. The 100th key is pressed at time $99T$.

$$99T > 790\mu\text{s}$$

Thus, the minimum value of T that does not discard any keys is approximately $7.98\mu\text{s}$.