

For  $t < 0$ , both switches are closed and the inductor appears as short circuit. Thus all current from voltage and current source flow through it, but in opposite directions.

$$\Rightarrow i_L(0^-) = i_L(0^+) = \frac{40V}{20\Omega} - 1A = 1A$$

Because of short, we have  $V(0^-) = V(0^+) = 0V$ .

With switches open, we have natural response of parallel RLC circuit.

$$\alpha = \frac{1}{2RC} = \frac{1}{2(5)0.05} = 2 \text{ s}^{-1}, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{5(0.05)}} = 2 \text{ s}^{-1}$$

Because  $\alpha = \omega_0$ , we have a critically damped response.

$$\Rightarrow V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

Now we can just plug values into Table 8.2 to find constants.

$$D_2 = V(t=0^+) = 0, \quad D_1 = \frac{1}{C} \left( \frac{-V(0^+)}{R} - i_L(0^+) \right) + \alpha D_2 = \frac{1}{0.05} \left( \frac{0}{R} - 1 \right) + 0 = -20$$

$$\Rightarrow \underline{V(t) = -20t e^{-2t} \text{ V}}$$

For  $i_L$ , we have various ways of finding the solution. We could integrate the voltage:

$$i_L(t) = \frac{1}{L} \int_0^t V(\tau) d\tau + i_L(0)$$

Or we could use the generic form of the solution to a critically damped natural response, using what we know about  $i_L(0^+)$  and  $\frac{di_L(0^+)}{dt}$ .

$$\Rightarrow i_L(t) = K_1 t e^{-2t} + K_2 e^{-2t}$$

$$i_L(0^+) = 1A = K_2, \quad L \frac{di_L(0^+)}{dt} = V(0^+) = 0 \Rightarrow \frac{di_L(0)}{dt} = K_1 - 2K_2 = 0$$

(continued)

1) (continued)

$$\text{We have } K_2 = 1A \quad \& \quad K_1 - 2K_2 = 0 \Rightarrow K_1 = 2K_2 = 2A$$

$$\text{Thus, } \bar{i}_L(t) = 2te^{-2t} + e^{-2t} \quad A$$

But, let's also solve using KCL, i.e.,

$$\bar{i}_R + \bar{i}_L + \bar{i}_C = 0 \Rightarrow \bar{i}_L(t) = -\bar{i}_R(t) - \bar{i}_C(t) = -\frac{v(t)}{R} - C \frac{dv(t)}{dt}$$

Using the voltage we found above, we have

$$\begin{aligned} \bar{i}_L(t) &= -\frac{1}{5}(-20te^{-2t}) - 0.05(-20e^{-2t} + 40te^{-2t}) \\ &= 4te^{-2t} + e^{-2t} - 2te^{-2t} = \underline{\underline{2te^{-2t} + e^{-2t} \quad A}} \end{aligned}$$

Same as above.

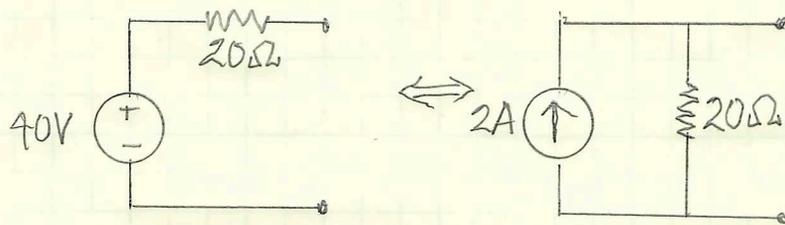
As a further check, you could confirm that  $L \frac{d\bar{i}_L(t)}{dt} = v(t)$  (it does).

2) Same as previous circuit except now switch on left closes at  $t=0$  instead of opening.

For  $t < 0$ , inductor is a short.  $\Rightarrow \bar{i}_L(0^-) = \bar{i}_L(0^+) = -1\text{A}$ .

$$V(0^-) = V(0^+) = 0\text{V}.$$

We have a forced response for  $t > 0$ . Convert Thevenin circuit on left of switch to its Norton equivalent.

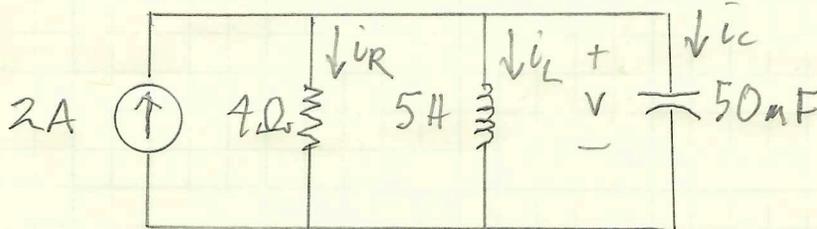


$$V_{oc} = V_{th} = 40\text{V}$$

$$I_{sc} = I_N = \frac{40\text{V}}{20\Omega} = 2\text{A}$$

$$R_{th} = R_N = 5\Omega$$

For  $t > 0$ , circuit appears as



$$5\Omega \parallel 20\Omega = 4\Omega$$

Initial conditions:  $\bar{i}_L(0^+) = -1\text{A}$   $V(0^+) = 0\text{V}$

Final conditions:  $\bar{i}_L(\infty) = 2\text{A}$   $V(\infty) = 0\text{V}$  (inductor again short)

For a forced parallel RLC circuit, we can use Table 8.3.

$$\alpha = \frac{1}{2RC} = \frac{1}{2(4)(0.05)} = 2.5\text{ s}^{-1} \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{5(0.05)}} = 2$$

$\alpha > \omega_0 \Rightarrow$  Overdamped response

Characteristic polynomial yields,  $s_{1,2} = -\alpha \pm (\alpha^2 - \omega_0^2)^{1/2} = \begin{cases} s_1 = -4 \\ s_2 = -1 \end{cases}$

$$\bar{i}_L(t) = \bar{i}_\infty + A_1' e^{s_1 t} + A_2' e^{s_2 t} = 2 + A_1' e^{-4t} + A_2' e^{-t} \text{ A}$$

$$\bar{i}_L(t=0) = 2 + A_1' + A_2' = -1 \quad \Rightarrow A_1' + A_2' = -3 \quad (*)$$

$$\frac{d\bar{i}_L(t=0)}{dt} = \frac{1}{L} V(0) = 0 = -4A_1' - A_2' \quad \Rightarrow -4A_1' - A_2' = 0 \quad (**)$$

(continued)

2) (continued)

$$\text{Add (*) and (**)} \Rightarrow -3A_1' = -3 \Rightarrow A_1' = 1$$

$$\text{Plugging this back into (*), we obtain } A_2' = -3 - A_1' = -4.$$

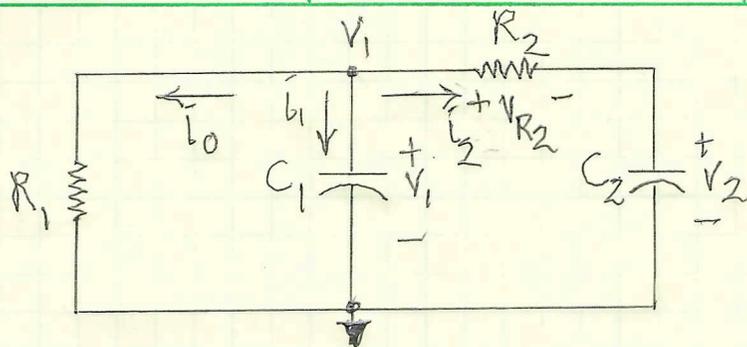
Putting this together, we get

$$\underline{\underline{i_L(t) = 2 + e^{-4t} - 4e^{-t} \text{ A}}}$$

For  $v(t)$ , we have  $v(t) = L \frac{di_L}{dt}$ .

$$\Rightarrow v(t) = 5H(-4e^{-4t} + 4e^{-t}) \cdot V = \underline{\underline{20(e^{-t} - e^{-4t}) \text{ V}}}$$

3)



$$\text{KCL: } \bar{i}_0 + \bar{i}_1 + \bar{i}_2 = 0$$

$$\bar{i}_0 = \frac{V_1}{R_1}, \quad \bar{i}_1 = C_1 \frac{dV_1}{dt}, \quad \bar{i}_2 = C_2 \frac{dV_2}{dt}$$

$$V_1 = V_2 + V_{R2} = V_2 + R_2 \bar{i}_2 = V_2 + R_2 C_2 \frac{dV_2}{dt} \quad (1)$$

Plugging in the current terms into KCL equation yields:

$$\frac{1}{R_1} V_1 + C_1 \frac{d}{dt} (V_1) + C_2 \frac{dV_2}{dt} = 0$$

Plugging in (1) to replace  $V_1$ , yields

$$\frac{1}{R_1} \left( V_2 + R_2 C_2 \frac{dV_2}{dt} \right) + C_1 \frac{d}{dt} \left( V_2 + R_2 C_2 \frac{dV_2}{dt} \right) + C_2 \frac{dV_2}{dt} = 0$$

$$= \frac{1}{R_1} V_2 + \frac{R_2 C_2}{R_1} \frac{dV_2}{dt} + C_1 \frac{dV_2}{dt} + R_2 C_1 C_2 \frac{d^2 V_2}{dt^2} + C_2 \frac{dV_2}{dt} = 0$$

$$= R_2 C_1 C_2 \frac{d^2 V_2}{dt^2} + \left( \frac{R_2 C_2}{R_1} + C_1 + C_2 \right) \frac{dV_2}{dt} + \frac{1}{R_1} V_2 = 0$$

This is acceptable, or we could divide through by coefficient of highest derivative,

$$\Rightarrow \frac{d^2 V_2}{dt^2} + \left( \frac{1}{R_1 C_1} + \frac{1}{R_2} \left[ \frac{C_1 + C_2}{C_1 C_2} \right] \right) \frac{dV_2}{dt} + \frac{1}{R_1 R_2 C_1 C_2} V_2 = 0$$

$$4) a) -42 \cos(200\pi t - 0.4) = 42 \cos(200\pi t + \pi - 0.4)$$

$$\Rightarrow \underline{\underline{42 e^{j(\pi - 0.4)}}} = 42 e^{j2.7416} = 42 \angle 157.08^\circ \text{ V} \leftarrow \text{any of these are fine}$$

Okay to write  $-42 e^{j0.4}$  but ideally the magnitude is non-negative.

$$b) 35^\circ = \frac{35}{180} \pi = 0.6109 \text{ radians}$$

$$6.2 \sin(200\pi t + 35^\circ) = \text{Re}[-j6.2 e^{j(200\pi t + 0.6109)}] \quad \text{Note: } -j = e^{-j\pi/2}$$

$$= \text{Re}[6.2 e^{j(200\pi t + 0.6109 - \frac{\pi}{2})}] \Rightarrow \underline{\underline{6.2 e^{j(0.6109 - \pi/2)}}}$$

$$= 6.2 e^{-j0.9599} = 6.2 \angle -55^\circ \text{ mA}$$

$$5) a) \tilde{V} = 8 e^{-j\pi/6}, \quad \omega = 200 \text{ rad/s}$$

$$\Rightarrow v(t) = \text{Re}[8 e^{-j\pi/6} e^{j200t}] = \underline{\underline{8 \cos(200t - \pi/6) \text{ V}}}$$

$$b) \tilde{V} = \sqrt{2} e^{j0.25}, \quad f = 10 \text{ kHz} \Rightarrow \omega = 2\pi f = 2\pi \times 10^4 \text{ rad/s}$$

$$\Rightarrow v(t) = \text{Re}[\sqrt{2} e^{j0.25} e^{j2\pi \times 10^4 t}] = \underline{\underline{\sqrt{2} \cos(2\pi \times 10^4 t + 0.25) \text{ V}}}$$

$$c) \tilde{I} = 42 \angle \pi/6 \text{ A}, \quad T = 10^{-6} \text{ s} \Rightarrow f = 10^6 \text{ Hz} \Rightarrow \omega = 2\pi \times 10^6 \text{ rad/s}$$

$$\Rightarrow i(t) = \text{Re}[42 e^{j\pi/6} e^{j2\pi \times 10^6 t}] = \underline{\underline{42 \cos(2\pi \times 10^6 t + \pi/6) \text{ A}}}$$