

## EE 331—COORDINATE SYSTEMS

CARTESIAN ( $x, y, z$ )

$$d\bar{I} = dx \hat{\mathbf{a}}_x + dy \hat{\mathbf{a}}_y + dz \hat{\mathbf{a}}_z \text{ [m]}$$

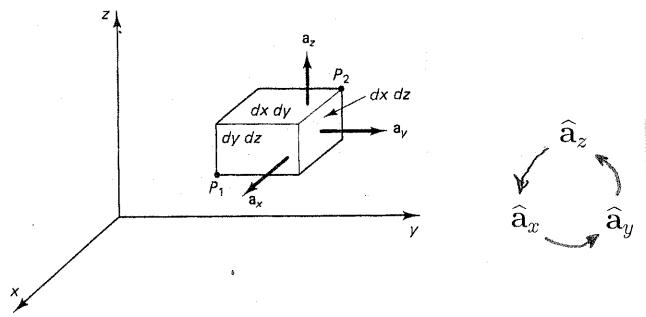
$$d\bar{\mathbf{S}} = \pm dy dz \hat{\mathbf{a}}_x \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm dx dz \hat{\mathbf{a}}_y \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm dx dy \hat{\mathbf{a}}_z \text{ [m}^2]$$

$$dv = dx dy dz \text{ [m}^3]$$

$$\bar{\mathbf{r}} = x \hat{\mathbf{a}}_x + y \hat{\mathbf{a}}_y + z \hat{\mathbf{a}}_z \text{ [m]}$$



CYLINDRICAL ( $\rho, \phi, z$ )

$$d\bar{I} = d\rho \hat{\mathbf{a}}_\rho + \rho d\phi \hat{\mathbf{a}}_\phi + dz \hat{\mathbf{a}}_z \text{ [m]}$$

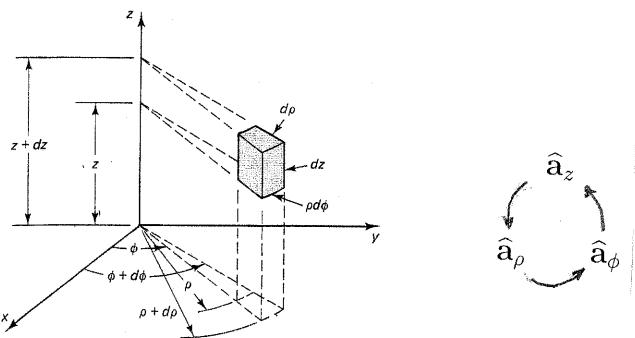
$$d\bar{\mathbf{S}} = \pm \rho d\phi dz \hat{\mathbf{a}}_\rho \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm d\rho dz \hat{\mathbf{a}}_\phi \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm \rho d\rho d\phi \hat{\mathbf{a}}_z \text{ [m}^2]$$

$$dv = \rho d\rho d\phi dz \text{ [m}^3]$$

$$\bar{\mathbf{r}} = \rho \hat{\mathbf{a}}_\rho + z \hat{\mathbf{a}}_z \text{ [m]}$$



CARTESIAN  $\rightarrow$  CYLINDRICAL

$$A_\rho = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_\rho = A_x \hat{\mathbf{a}}_x \cdot \hat{\mathbf{a}}_\rho + A_y \hat{\mathbf{a}}_y \cdot \hat{\mathbf{a}}_\rho$$

$$A_\phi = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_\phi = A_x \hat{\mathbf{a}}_x \cdot \hat{\mathbf{a}}_\phi + A_y \hat{\mathbf{a}}_y \cdot \hat{\mathbf{a}}_\phi$$

$$A_z = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_z = A_z$$

$$\bullet \bar{\mathbf{A}} = A_\rho \hat{\mathbf{a}}_\rho + A_\phi \hat{\mathbf{a}}_\phi + A_z \hat{\mathbf{a}}_z$$

CYLINDRICAL  $\rightarrow$  CARTESIAN

$$A_x = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_x = A_\rho \hat{\mathbf{a}}_\rho \cdot \hat{\mathbf{a}}_x + A_\phi \hat{\mathbf{a}}_\phi \cdot \hat{\mathbf{a}}_x$$

$$A_y = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_y = A_\rho \hat{\mathbf{a}}_\rho \cdot \hat{\mathbf{a}}_y + A_\phi \hat{\mathbf{a}}_\phi \cdot \hat{\mathbf{a}}_y$$

$$A_z = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_z = A_z$$

$$\bullet \bar{\mathbf{A}} = A_x \hat{\mathbf{a}}_x + A_y \hat{\mathbf{a}}_y + A_z \hat{\mathbf{a}}_z$$

SPHERICAL ( $r, \theta, \phi$ )

$$d\bar{I} = dr \hat{\mathbf{a}}_r + r d\theta \hat{\mathbf{a}}_\theta + r \sin \theta d\phi \hat{\mathbf{a}}_\phi \text{ [m]}$$

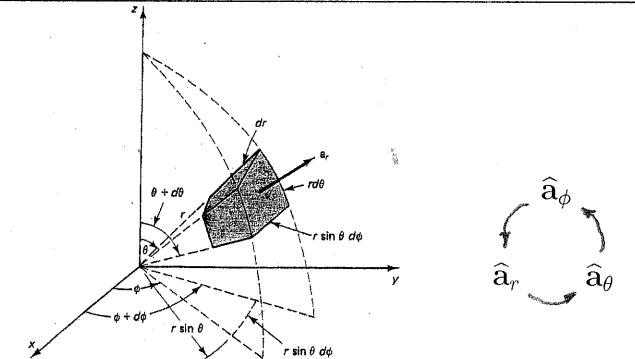
$$d\bar{\mathbf{S}} = \pm r^2 \sin \theta d\theta d\phi \hat{\mathbf{a}}_r \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm r \sin \theta dr d\phi \hat{\mathbf{a}}_\theta \text{ [m}^2]$$

$$d\bar{\mathbf{S}} = \pm r dr d\theta \hat{\mathbf{a}}_\phi \text{ [m}^2]$$

$$dv = r^2 \sin \theta dr d\theta d\phi \text{ [m}^3]$$

$$\bar{\mathbf{r}} = r \hat{\mathbf{a}}_r \text{ [m]}$$



CARTESIAN  $\rightarrow$  SPHERICAL

$$A_r = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_r = A_x \hat{\mathbf{a}}_x \cdot \hat{\mathbf{a}}_r + A_y \hat{\mathbf{a}}_y \cdot \hat{\mathbf{a}}_r + A_z \hat{\mathbf{a}}_z \cdot \hat{\mathbf{a}}_r$$

$$A_\theta = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_\theta = A_x \hat{\mathbf{a}}_x \cdot \hat{\mathbf{a}}_\theta + A_y \hat{\mathbf{a}}_y \cdot \hat{\mathbf{a}}_\theta + A_z \hat{\mathbf{a}}_z \cdot \hat{\mathbf{a}}_\theta$$

$$A_\phi = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_\phi = A_x \hat{\mathbf{a}}_x \cdot \hat{\mathbf{a}}_\phi + A_y \hat{\mathbf{a}}_y \cdot \hat{\mathbf{a}}_\phi$$

$$\bullet \bar{\mathbf{A}} = A_r \hat{\mathbf{a}}_r + A_\theta \hat{\mathbf{a}}_\theta + A_\phi \hat{\mathbf{a}}_\phi$$

SPHERICAL  $\rightarrow$  CARTESIAN

$$A_x = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_x = A_r \hat{\mathbf{a}}_r \cdot \hat{\mathbf{a}}_x + A_\theta \hat{\mathbf{a}}_\theta \cdot \hat{\mathbf{a}}_x + A_\phi \hat{\mathbf{a}}_\phi \cdot \hat{\mathbf{a}}_x$$

$$A_y = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_y = A_r \hat{\mathbf{a}}_r \cdot \hat{\mathbf{a}}_y + A_\theta \hat{\mathbf{a}}_\theta \cdot \hat{\mathbf{a}}_y + A_\phi \hat{\mathbf{a}}_\phi \cdot \hat{\mathbf{a}}_y$$

$$A_z = \bar{\mathbf{A}} \cdot \hat{\mathbf{a}}_z = A_r \hat{\mathbf{a}}_r \cdot \hat{\mathbf{a}}_z + A_\theta \hat{\mathbf{a}}_\theta \cdot \hat{\mathbf{a}}_z$$

$$\bullet \bar{\mathbf{A}} = A_x \hat{\mathbf{a}}_x + A_y \hat{\mathbf{a}}_y + A_z \hat{\mathbf{a}}_z$$

CONVERSION FACTORS

CARTESIAN/CYLINDRICAL

$$\begin{aligned} x &= \rho \cos \phi & \rho &= \sqrt{x^2 + y^2} \\ y &= \rho \sin \phi & \phi &= \tan^{-1}(y/x) \\ z &= z & z &= z \end{aligned}$$

CARTESIAN/SPHERICAL

$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \cos^{-1}(z/r) \\ z &= r \cos \theta & \phi &= \tan^{-1}(y/x) \end{aligned}$$

.	$\hat{\mathbf{a}}_\rho$	$\hat{\mathbf{a}}_\phi$	$\hat{\mathbf{a}}_z$
$\hat{\mathbf{a}}_x$	$\cos \phi$	$-\sin \phi$	0
$\hat{\mathbf{a}}_y$	$\sin \phi$	$\cos \phi$	0
$\hat{\mathbf{a}}_z$	0	0	1
.	$\hat{\mathbf{a}}_r$	$\hat{\mathbf{a}}_\theta$	$\hat{\mathbf{a}}_\phi$
$\hat{\mathbf{a}}_x$	$\sin \theta \cos \phi$	$\cos \theta \cos \phi$	$-\sin \phi$
$\hat{\mathbf{a}}_y$	$\sin \theta \sin \phi$	$\cos \theta \sin \phi$	$\cos \phi$
$\hat{\mathbf{a}}_z$	$\cos \theta$	$-\sin \theta$	0